

Periodic striped ground states in Ising models with competing interactions

Alessandro Giuliani

Università degli Studi Roma Tre

Based on joint works with J. Lebowitz, E. Lieb and R. Seiringer

IHP Paris, January 26, 2016

Outline

- 1 Introduction
- 2 Ising models with competing interactions
- 3 Sketch of the proof

Outline

- 1 Introduction
- 2 Ising models with competing interactions
- 3 Sketch of the proof

Periodic patterns

The spontaneous emergence of periodic states is an ubiquitous phenomenon in nature.

Nevertheless, a fundamental understanding of why crystals, or ordered patterns, form is still missing.

In this talk I would like to focus on the phenomenon of formation of periodic arrays of **stripes** or **slabs**, which are observed in a variety of systems, ranging from magnetic films to superconductors, polymer suspensions, twinned martensites, etc.

Periodic patterns

The spontaneous emergence of periodic states is an ubiquitous phenomenon in nature.

Nevertheless, a fundamental understanding of why crystals, or ordered patterns, form is still missing.

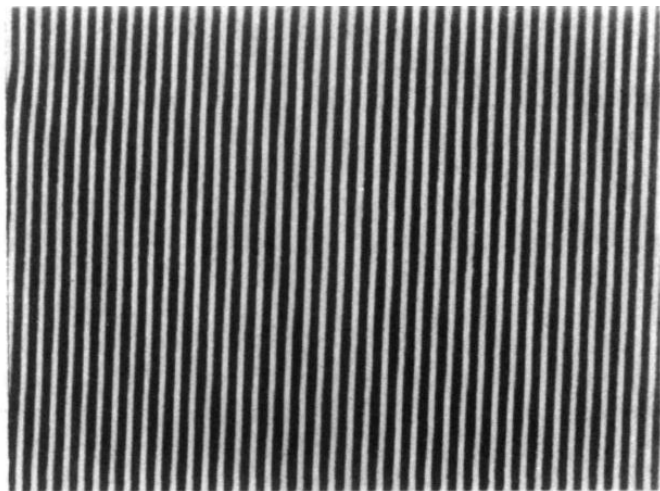
In this talk I would like to focus on the phenomenon of formation of periodic arrays of **stripes** or **slabs**, which are observed in a variety of systems, ranging from magnetic films to superconductors, polymer suspensions, twinned martensites, etc.

Stripes



Fig. 3. Magnetic image of the 308 nm Py film ($6\mu\text{m}$ scan). The half period is 220 ± 30 nm, slightly smaller than the film thickness.

Stripes



Magnetic garnet film $(\text{YGdTm})_3(\text{FeGa})_6\text{O}_2$ at $H = 0$

Competing interactions

The basic mechanism behind stripe formation seems to be the **competition** between a short-range attractive and a long-range repulsive interaction.

The resulting **frustration** induces the system to form mesoscopic islands of a uniform phase, which alternate regularly on the scale of the whole sample.

Striped and slabbed patterns

Theoretically, the understanding of these regular patterns is based on a variational computation of the “best energy” among a selected class of periodic states.

Remarkably, in many different situations, the “best state” seems to be striped or slabbed. But why?

Outline

- 1 Introduction
- 2 Ising models with competing interactions
- 3 Sketch of the proof

A standard model for competing interactions

In many situations, the following Hamiltonian is the simplest realistic model for pattern formation in systems with competing interactions:

$$H = -J \sum_{\langle \mathbf{x}, \mathbf{y} \rangle} (\sigma_{\mathbf{x}} \sigma_{\mathbf{y}} - 1) + \frac{1}{2} \sum_{\mathbf{x} \neq \mathbf{y}} \frac{(\sigma_{\mathbf{x}} \sigma_{\mathbf{y}} - 1)}{|\mathbf{x} - \mathbf{y}|^p}$$

The long range interaction can model:

- a Coulomb potential ($p = 1$),
- a dipolar potential ($p = 3$).

More general values of p describe a “generic” antiferromagnetic power law potential.

A standard model for competing interactions

In many situations, the following Hamiltonian is the simplest realistic model for pattern formation in systems with competing interactions:

$$H = -J \sum_{\langle \mathbf{x}, \mathbf{y} \rangle} (\sigma_{\mathbf{x}} \sigma_{\mathbf{y}} - 1) + \frac{1}{2} \sum_{\mathbf{x} \neq \mathbf{y}} \frac{(\sigma_{\mathbf{x}} \sigma_{\mathbf{y}} - 1)}{|\mathbf{x} - \mathbf{y}|^p}$$

The long range interaction can model:

- a Coulomb potential ($p = 1$),
- a dipolar potential ($p = 3$).

More general values of p describe a “generic” antiferromagnetic power law potential.

A standard model for competing interactions

In many situations, the following Hamiltonian is the simplest realistic model for pattern formation in systems with competing interactions:

$$H = -J \sum_{\langle \mathbf{x}, \mathbf{y} \rangle} (\sigma_{\mathbf{x}} \sigma_{\mathbf{y}} - 1) + \frac{1}{2} \sum_{\mathbf{x} \neq \mathbf{y}} \frac{(\sigma_{\mathbf{x}} \sigma_{\mathbf{y}} - 1)}{|\mathbf{x} - \mathbf{y}|^p}$$

The long range interaction can model:

- a Coulomb potential ($p = 1$),
- a dipolar potential ($p = 3$).

More general values of p describe a “generic” antiferromagnetic power law potential.

A standard model for competing interactions

In many situations, the following Hamiltonian is the simplest realistic model for pattern formation in systems with competing interactions:

$$H = -J \sum_{\langle \mathbf{x}, \mathbf{y} \rangle} (\sigma_{\mathbf{x}} \sigma_{\mathbf{y}} - 1) + \frac{1}{2} \sum_{\mathbf{x} \neq \mathbf{y}} \frac{(\sigma_{\mathbf{x}} \sigma_{\mathbf{y}} - 1)}{|\mathbf{x} - \mathbf{y}|^p}$$

The long range interaction can model:

- a Coulomb potential ($p = 1$),
- a dipolar potential ($p = 3$).

More general values of p describe a “generic” antiferromagnetic power law potential.

A standard model for competing interactions

In many situations, the following Hamiltonian is the simplest realistic model for pattern formation in systems with competing interactions:

$$H = -J \sum_{\langle \mathbf{x}, \mathbf{y} \rangle} (\sigma_{\mathbf{x}} \sigma_{\mathbf{y}} - 1) + \frac{1}{2} \sum_{\mathbf{x} \neq \mathbf{y}} \frac{(\sigma_{\mathbf{x}} \sigma_{\mathbf{y}} - 1)}{|\mathbf{x} - \mathbf{y}|^p}$$

The long range interaction can model:

- a Coulomb potential ($p = 1$),
- a dipolar potential ($p = 3$).

More general values of p describe a “generic” antiferromagnetic power law potential.

Known facts about the ground state

What are the ground states of the system?

Limiting cases:

- $J = +\infty$: homogeneous FM state
- $J = 0$: AF state (by RP: Fröhlich-Israel-Lieb-Simon 1978)

The FM state is stable for J large, for all $p > d + 1$
(Ginibre-Grossmann-Ruelle 1966)

The AF state is stable for $J \gtrsim 0$ for all d, p .

If $p > d + 1$, the FM transition line can be computed exactly (G-Lebowitz-Lieb 2011):

$$J = J_c(p) = \frac{1}{2} \sum_{\mathbf{y} \in \mathbb{Z}^d} \frac{|y_1|}{|\mathbf{y}|^p}$$

Known facts about the ground state

What are the ground states of the system?

Limiting cases:

- $J = +\infty$: homogeneous FM state
- $J = 0$: AF state (by RP: Fröhlich-Israel-Lieb-Simon 1978)

The FM state is stable for J large, for all $p > d + 1$
(Ginibre-Grossmann-Ruelle 1966)

The AF state is stable for $J \gtrsim 0$ for all d, p .

If $p > d + 1$, the FM transition line can be computed exactly (G-Lebowitz-Lieb 2011):

$$J = J_c(p) = \frac{1}{2} \sum_{\mathbf{y} \in \mathbb{Z}^d} \frac{|y_1|}{|\mathbf{y}|^p}$$

Known facts about the ground state

What are the ground states of the system?

Limiting cases:

- $J = +\infty$: homogeneous FM state
- $J = 0$: AF state (by RP: Fröhlich-Israel-Lieb-Simon 1978)

The FM state is stable for J large, for all $p > d + 1$
(Ginibre-Grossmann-Ruelle 1966)

The AF state is stable for $J \gtrsim 0$ for all d, p .

If $p > d + 1$, the FM transition line can be computed exactly (G-Lebowitz-Lieb 2011):

$$J = J_c(p) = \frac{1}{2} \sum_{\mathbf{y} \in \mathbb{Z}^d} \frac{|y_1|}{|\mathbf{y}|^p}$$

Known facts about the ground state

What are the ground states of the system?

Limiting cases:

- $J = +\infty$: homogeneous FM state
- $J = 0$: AF state (by RP: Fröhlich-Israel-Lieb-Simon 1978)

The FM state is stable for J large, for all $p > d + 1$
(Ginibre-Grossmann-Ruelle 1966)

The AF state is stable for $J \gtrsim 0$ for all d, p .

If $p > d + 1$, the FM transition line can be computed exactly (G-Lebowitz-Lieb 2011):

$$J = J_c(p) = \frac{1}{2} \sum_{\mathbf{y} \in \mathbb{Z}^d} \frac{|y_1|}{|\mathbf{y}|^p}$$

Known facts about the ground state

What are the ground states of the system?

Limiting cases:

- $J = +\infty$: homogeneous FM state
- $J = 0$: AF state (by RP: Fröhlich-Israel-Lieb-Simon 1978)

The FM state is stable for J large, for all $p > d + 1$
(Ginibre-Grossmann-Ruelle 1966)

The AF state is stable for $J \gtrsim 0$ for all d, p .

If $p > d + 1$, the FM transition line can be computed exactly (G-Lebowitz-Lieb 2011):

$$J = J_c(p) = \frac{1}{2} \sum_{\mathbf{y} \in \mathbb{Z}^d} \frac{|y_1|}{|\mathbf{y}|^p}$$

Known facts about the ground state

What are the ground states of the system?

Limiting cases:

- $J = +\infty$: homogeneous FM state
- $J = 0$: AF state (by RP: Fröhlich-Israel-Lieb-Simon 1978)

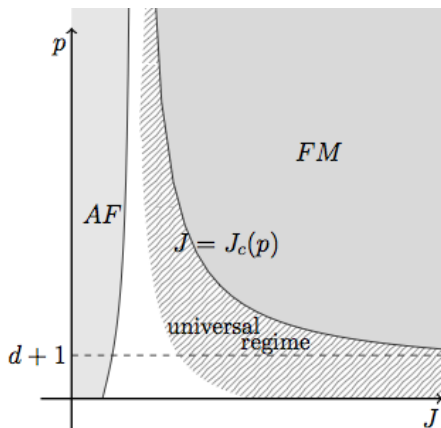
The FM state is stable for J large, for all $p > d + 1$
(Ginibre-Grossmann-Ruelle 1966)

The AF state is stable for $J \gtrsim 0$ for all d, p .

If $p > d + 1$, the FM transition line can be computed exactly (G-Lebowitz-Lieb 2011):

$$J = J_c(p) = \frac{1}{2} \sum_{\mathbf{y} \in \mathbb{Z}^d} \frac{|y_1|}{|\mathbf{y}|^p}$$

The expected ground state phase diagram



What happens in the intermediate region?

Expected: **periodic patterns!**

Which periodic patterns?

Standard procedure: minimize the energy among a class of periodic states, say stripes and checkerboard. If $d = 2$, in the universal regime:

$$\begin{array}{ll}
 \boxed{2 < p < 3} & e_s \sim -J^{-\frac{p-2}{3-p}}, \quad e_c \sim -J^{-\frac{p-2}{3-p}} \\
 \boxed{p = 3} & e_s \sim -e^{-J/2}, \quad e_c \sim -e^{-J/2} \\
 \boxed{3 < p \leq 4} & e_s \sim -(J_c - J)^{\frac{p-2}{p-3}}, \quad e_c \sim -(J_c - J)^{\frac{p-2}{p-3}} \\
 \boxed{p > 4} & e_s \sim -(J_c - J)^{\frac{p-2}{p-3}}, \quad e_c \sim -(J_c - J)^2
 \end{array}$$

In all cases, by computing the prefactors, we find that $e_s < e_c$: the best configuration seems to be the one consisting of **periodic stripes** of width $h^*(J)$.

Which periodic patterns?

Standard procedure: minimize the energy among a class of periodic states, say stripes and checkerboard. If $d = 2$, in the universal regime:

$$\begin{array}{ll}
 \boxed{2 < p < 3} & e_s \sim -J^{-\frac{p-2}{3-p}}, \quad e_c \sim -J^{-\frac{p-2}{3-p}} \\
 \boxed{p = 3} & e_s \sim -e^{-J/2}, \quad e_c \sim -e^{-J/2} \\
 \boxed{3 < p \leq 4} & e_s \sim -(J_c - J)^{\frac{p-2}{p-3}}, \quad e_c \sim -(J_c - J)^{\frac{p-2}{p-3}} \\
 \boxed{p > 4} & e_s \sim -(J_c - J)^{\frac{p-2}{p-3}}, \quad e_c \sim -(J_c - J)^2
 \end{array}$$

In all cases, by computing the prefactors, we find that $e_s < e_c$: the best configuration seems to be the one consisting of **periodic stripes** of width $h^*(J)$.

Rigorous results

- 1 If the ground state is striped, then it is periodic.
In particular, in $d = 1$ it is always periodic
(G-Lebowitz-Lieb 2006)
- 2 Upper and lower bounds on the g.s. energy,
matching at the dominant order (G-Lebowitz-Lieb
2006, 2007, 2011)
- 3 $p > 2d$: upper lower bounds on the g.s. energy,
matching at the 1st subdominant order
(G-Lieb-Seiringer 2013)

Methods: RP + decimation + localization estimates

Rigorous results

- 1 If the ground state is striped, then it is periodic.
In particular, in $d = 1$ it is always periodic
(G-Lebowitz-Lieb 2006)
- 2 Upper and lower bounds on the g.s. energy,
matching at the dominant order (G-Lebowitz-Lieb
2006, 2007, 2011)
- 3 $p > 2d$: upper lower bounds on the g.s. energy,
matching at the 1st subdominant order
(G-Lieb-Seiringer 2013)

Methods: RP + decimation + localization estimates

Rigorous results

- 1 If the ground state is striped, then it is periodic.
In particular, in $d = 1$ it is always periodic
(G-Lebowitz-Lieb 2006)
- 2 Upper and lower bounds on the g.s. energy,
matching at the dominant order (G-Lebowitz-Lieb
2006, 2007, 2011)
- 3 $p > 2d$: upper lower bounds on the g.s. energy,
matching at the 1^{st} subdominant order
(G-Lieb-Seiringer 2013)

Methods: RP + decimation + localization estimates

Other results, I

Our methods have been generalized and applied to other models:

- 1 1D continuum functionals with magnetic field
(G-Lebowitz-Lieb): RP + *convexity*;
- 2 1D models where the FM interaction is not n.n.
(Buttà-Esposito-G-Marra): RP + *coarse graining*;
- 3 anisotropic 2D system for martensitic phase transitions
(G-Müller): RP + *localization bounds*;
- 4 isotropic 2D magnetic models with in-plane spins
(G-Lebowitz-Lieb): FM RP + AF RP.

Other results, I

Our methods have been generalized and applied to other models:

- 1 1D continuum functionals with magnetic field
(G-Lebowitz-Lieb): RP + *convexity*;
- 2 1D models where the FM interaction is not n.n.
(Buttà-Esposito-G-Marra): RP + *coarse graining*;
- 3 anisotropic 2D system for martensitic phase transitions (G-Müller): RP + *localization bounds*;
- 4 isotropic 2D magnetic models with in-plane spins (G-Lebowitz-Lieb): FM RP + AF RP.

Other results, I

Our methods have been generalized and applied to other models:

- 1 1D continuum functionals with magnetic field
(G-Lebowitz-Lieb): RP + *convexity*;
- 2 1D models where the FM interaction is not n.n.
(Buttà-Esposito-G-Marra): RP + *coarse graining*;
- 3 anisotropic 2D system for martensitic phase transitions
(G-Müller): RP + *localization bounds*;
- 4 isotropic 2D magnetic models with in-plane spins
(G-Lebowitz-Lieb): FM RP + AF RP.

Other results, I

Our methods have been generalized and applied to other models:

- 1 1D continuum functionals with magnetic field
(G-Lebowitz-Lieb): RP + *convexity*;
- 2 1D models where the FM interaction is not n.n.
(Buttà-Esposito-G-Marra): RP + *coarse graining*;
- 3 anisotropic 2D system for martensitic phase transitions
(G-Müller): RP + *localization bounds*;
- 4 isotropic 2D magnetic models with in-plane spins
(G-Lebowitz-Lieb): FM RP + AF RP.

Other results, II

More results on related models (in the continuum):

In $d = 1$:

- Periodicity of 1D minimizers

(Chen-Oshita, Hubbard, Müller, Kohn-Müller, ...)

In $d \geq 2$:

- Computat'n of the ground state energy at dominant order
- Proof of the self-similarity of the finite volume free energy
- Derivation of effective functionals for meso-patterns
- Identification of the best periodic pattern among selected class of periodic states

(Alberti, Choksi, Conti, Kohn, Müller, Muratov, Otto, Sandier, Serfaty, ...)

Other results, II

More results on related models (in the continuum):

In $d = 1$:

- Periodicity of 1D minimizers

(Chen-Oshita, Hubbard, Müller, Kohn-Müller, ...)

In $d \geq 2$:

- Computat'n of the ground state energy at dominant order
- Proof of the self-similarity of the finite volume free energy
- Derivation of effective functionals for meso-patterns
- Identification of the best periodic pattern among selected class of periodic states

(Alberti, Choksi, Conti, Kohn, Müller, Muratov, Otto, Sandier, Serfaty, ...)

Periodicity in $d \geq 2$

There are just a few very special cases for which one can prove the existence of non-trivial periodic structures in $d \geq 2$. Remarkable: existence of triangular lattice by Heilmann-Radin, Theil, Sütö.

Open problem: prove (or disprove) the periodicity of the minimizers for our model, or related models in the continuum, in $d \geq 2$ and $p \geq 1$.

In this talk, I present the first proof of periodicity of the minimizers, for all $d \geq 2$ and $p > 2d$, in a left neighborhood of the FM transition line.

Periodicity in $d \geq 2$

There are just a few very special cases for which one can prove the existence of non-trivial periodic structures in $d \geq 2$. Remarkable: existence of triangular lattice by Heilmann-Radin, Theil, Süto.

Open problem: prove (or disprove) the periodicity of the minimizers for our model, or related models in the continuum, in $d \geq 2$ and $p \geq 1$.

In this talk, I present the first proof of periodicity of the minimizers, for all $d \geq 2$ and $p > 2d$, in a left neighborhood of the FM transition line.

Periodicity in $d \geq 2$

There are just a few very special cases for which one can prove the existence of non-trivial periodic structures in $d \geq 2$. Remarkable: existence of triangular lattice by Heilmann-Radin, Theil, Sütö.

Open problem: prove (or disprove) the periodicity of the minimizers for our model, or related models in the continuum, in $d \geq 2$ and $p \geq 1$.

In this talk, I present the first proof of periodicity of the minimizers, for all $d \geq 2$ and $p > 2d$, in a left neighborhood of the FM transition line.

Main results

Theorem [G-Seiringer]. *Let $d \geq 2$, $p > 2d$ and $J_c = J_c(p)$ be the location of the FM transition line.*

There exists $\epsilon > 0$ such that, if $J_c - \epsilon < J < J_c$, then, in any finite box, the ground state with “optimal striped boundary conditions” is unique.

Such ground state is periodic and striped, with stripes all of width $h^(J)$.*

Remarks

- Our theorem is based on quantitative lower bounds on the excess energy of generic spin states with optimal striped boundary conditions.
- Our result can be restated by saying that all the infinite periodic striped configurations are (strictly stable) infinite volume ground states.
- We also prove that any infinite volume g.s., invariant under translations by $d - 1$ independent integer vectors, consists of two periodic striped halves separated by a finite interface.

Remarks

- Our theorem is based on quantitative lower bounds on the excess energy of generic spin states with optimal striped boundary conditions.
- Our result can be restated by saying that all the infinite periodic striped configurations are (strictly stable) infinite volume ground states.
- We also prove that any infinite volume g.s., invariant under translations by $d - 1$ independent integer vectors, consists of two periodic striped halves separated by a finite interface.

Remarks

- Our theorem is based on quantitative lower bounds on the excess energy of generic spin states with optimal striped boundary conditions.
- Our result can be restated by saying that all the infinite periodic striped configurations are (strictly stable) infinite volume ground states.
- We also prove that any infinite volume g.s., invariant under translations by $d - 1$ independent integer vectors, consists of two periodic striped halves separated by a finite interface.

Outline

- 1 Introduction
- 2 Ising models with competing interactions
- 3 Sketch of the proof

Main steps

Restrict to $d = 2$ and $p > 4$, for simplicity.

The main steps of the proof are:

- 1 Representation of the energy in terms of droplet self-energies and droplet-droplet interactions.
- 2 Localization of the droplets' energy functional in **bad tiles** of side ℓ containing at least one corner and **good striped regions**.
- 3 Key fact: the localized energy of the bad tiles has an excess energy $\propto N_c$.
- 4 The localized energy of the good regions can be bounded from below via **reflection positivity** and a (subtle) control of the boundary error.

Main steps

Restrict to $d = 2$ and $p > 4$, for simplicity.

The main steps of the proof are:

- 1 Representation of the energy in terms of droplet self-energies and droplet-droplet interactions.
- 2 Localization of the droplets' energy functional in **bad tiles** of side ℓ containing at least one corner and **good striped regions**.
- 3 Key fact: the localized energy of the bad tiles has an excess energy $\propto N_c$.
- 4 The localized energy of the good regions can be bounded from below via **reflection positivity** and a (subtle) control of the boundary error.

Main steps

Restrict to $d = 2$ and $p > 4$, for simplicity.

The main steps of the proof are:

- 1 Representation of the energy in terms of droplet self-energies and droplet-droplet interactions.
- 2 Localization of the droplets' energy functional in **bad tiles** of side ℓ containing at least one corner and **good striped regions**.
- 3 Key fact: the localized energy of the bad tiles has an excess energy $\propto N_c$.
- 4 The localized energy of the good regions can be bounded from below via **reflection positivity** and a (subtle) control of the boundary error.

Main steps

Restrict to $d = 2$ and $p > 4$, for simplicity.

The main steps of the proof are:

- 1 Representation of the energy in terms of droplet self-energies and droplet-droplet interactions.
- 2 Localization of the droplets' energy functional in **bad tiles** of side ℓ containing at least one corner and **good striped regions**.
- 3 Key fact: the localized energy of the bad tiles has an excess energy $\propto N_c$.
- 4 The localized energy of the good regions can be bounded from below via **reflection positivity** and a (subtle) control of the boundary error.

Main steps

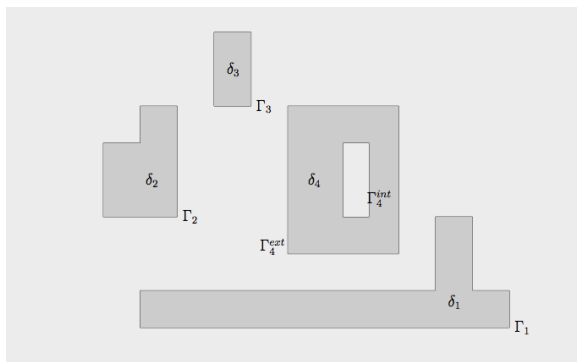
Restrict to $d = 2$ and $p > 4$, for simplicity.

The main steps of the proof are:

- 1 Representation of the energy in terms of droplet self-energies and droplet-droplet interactions.
- 2 Localization of the droplets' energy functional in **bad tiles** of side ℓ containing at least one corner and **good striped regions**.
- 3 Key fact: the localized energy of the bad tiles has an excess energy $\propto N_c$.
- 4 The localized energy of the good regions can be bounded from below via **reflection positivity** and a (subtle) control of the boundary error.

The droplet representation

In the presence of $+$ boundary conditions, we define the droplets δ_i to be the maximal connected regions of negative spins. Their boundaries Γ_i are the usual low-temperature contours of the Ising model.



The droplet representation

The total energy can be rewritten as:

$$H = \sum_i [2J|\Gamma_i| + U(\delta_i)] + \sum_{i < j} W(\delta_i, \delta_j)$$

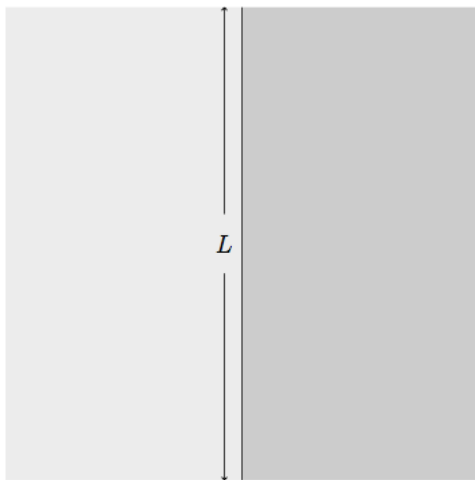
where:

$$U(\delta) = -2 \sum_{\mathbf{x} \in \delta} \sum_{\mathbf{y} \in \mathbb{Z}^2 \setminus \delta} \frac{1}{|\mathbf{x} - \mathbf{y}|^p}$$

$$W(\delta, \delta') = 4 \sum_{\mathbf{x} \in \delta} \sum_{\mathbf{y} \in \delta'} \frac{1}{|\mathbf{x} - \mathbf{y}|^p}$$

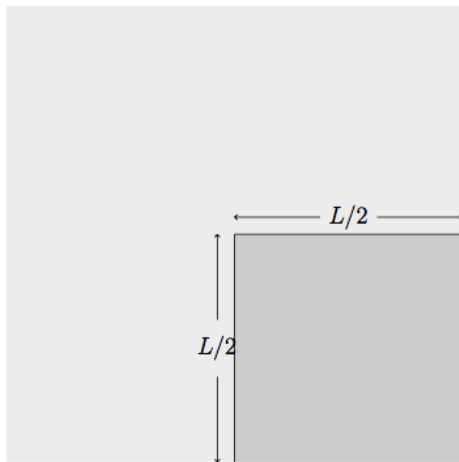
Note: the droplet-droplet interaction is positive.

Energy of a droplet ($p > 4$)



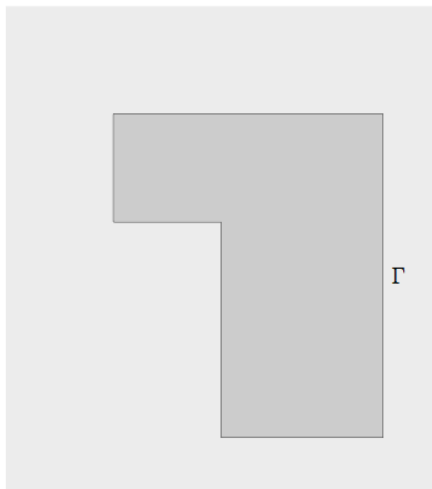
$$E = (2J - 2J_c)L$$

Energy of a droplet ($p > 4$)



$$E = (2J - 2J_c)L + \kappa_c$$

Energy of a droplet ($p > 4$)



$$E \geq 2(J - J_c)|\Gamma| + \kappa_c N_c$$

Corners

Take home message: **corners** cost a finite energy!
They look like **elementary excitations**.

However: how do we eliminate corners by local moves? How do we exclude that their presence does not decrease the interaction energy substantially?

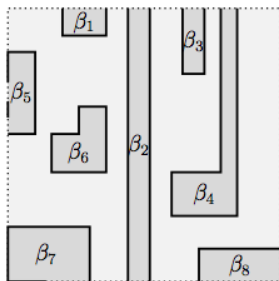
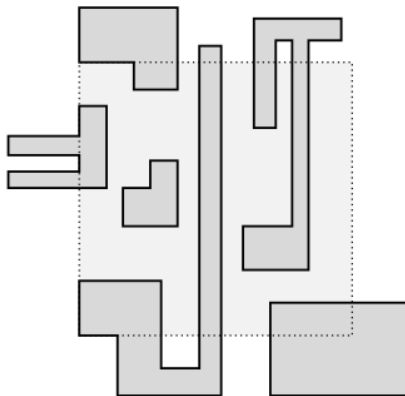
Corners

Take home message: **corners** cost a finite energy!
They look like **elementary excitations**.

However: how do we eliminate corners by local moves? How do we exclude that their presence does not decrease the interaction energy substantially?

Localization

We **localize** in bad tiles T_i of side $h^* \ll \ell \ll (J_c - J)^{-1}$ and good regions G_i .



Lower bounds on the local energies

As far as $W(\delta_i, \delta_j)$ is concerned, we just neglect the terms with δ_i, δ_j belonging to different tiles T_i or good regions G_i .

The local energy of a bad tile is $\geq e_s(h^*)\ell^2 + n_c(T)$.

Non trivial part: lower bound on the energy of the good regions, of the form

$$E_G \geq e_s(h^*)|G| - (J_c - J)|\partial G| + \sum_{h \neq h^*} (e_s(h) - e_s(h^*))A_h(G)$$

with $A_h(G)$ the area covered by stripes of width h .

Lower bounds on the local energies

As far as $W(\delta_i, \delta_j)$ is concerned, we just neglect the terms with δ_i, δ_j belonging to different tiles T_i or good regions G_i .

The local energy of a bad tile is $\geq e_s(h^*)\ell^2 + n_c(T)$.

Non trivial part: lower bound on the energy of the good regions, of the form

$$E_G \geq e_s(h^*)|G| - (J_c - J)|\partial G| + \sum_{h \neq h^*} (e_s(h) - e_s(h^*))A_h(G)$$

with $A_h(G)$ the area covered by stripes of width h .

Lower bounds on the local energies

As far as $W(\delta_i, \delta_j)$ is concerned, we just neglect the terms with δ_i, δ_j belonging to different tiles T_i or good regions G_i .

The local energy of a bad tile is $\geq e_s(h^*)\ell^2 + n_c(T)$.

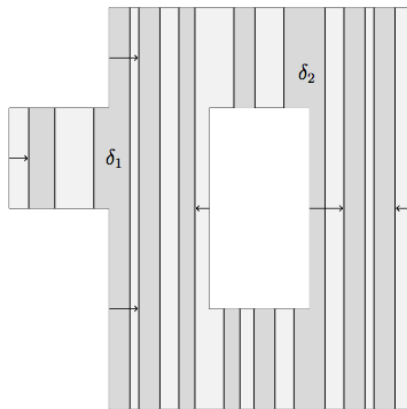
Non trivial part: lower bound on the energy of the good regions, of the form

$$E_G \geq e_s(h^*)|G| - (J_c - J)|\partial G| + \sum_{h \neq h^*} (e_s(h) - e_s(h^*))A_h(G)$$

with $A_h(G)$ the area covered by stripes of width h .

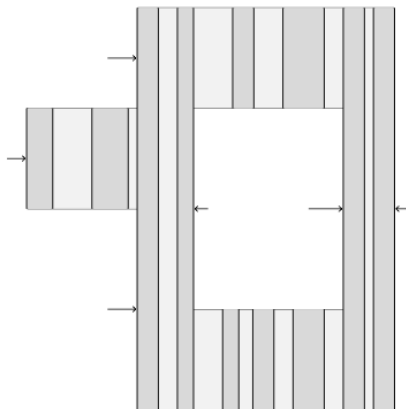
Lower bounds on the local energy of the good regions, I

A good region G can have a complicated shape. We deform and slice G , thus reducing it to a union of rectangles, keeping track of boundary errors.



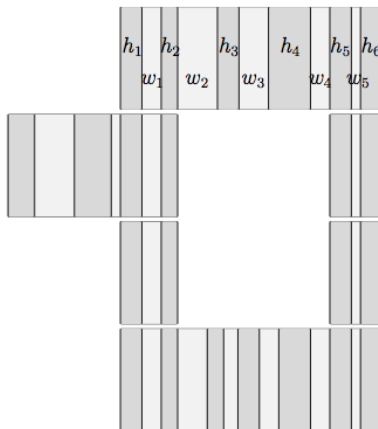
Lower bounds on the local energy of the good regions, II

We first move the vertical boundaries to the interior, so that they coincide with boundaries of the rectangular droplets.



Lower bounds on the local energy of the good regions, III

Next we slice in horizontal slices, and show that we only pay a boundary error from the **external boundary**, of the order $\sim (J_c - J)|\partial G|$.



Reflection positivity

Finally, in order to get an optimal bound on the energy of a slice, we use **block reflection positivity**, as developed by G-Lebowitz-Lieb in the study of the 1D version of our model.

$$\begin{array}{c}
 \boxed{h_1} \quad \boxed{h_2} \quad \boxed{h_3} \quad \boxed{h_4} \quad \geq \\
 \geq \frac{1}{2} \boxed{h_4} \quad \boxed{h_3} \quad \boxed{h_3} \quad \boxed{h_4} \quad + \quad \frac{1}{2} \boxed{h_1} \quad \boxed{h_2} \quad \boxed{h_2} \quad \boxed{h_1}
 \end{array}$$

Summary

- Ising models with competing interactions are a natural “standard” model for stripe formation.
- Variational computations suggest that in the universal regime, where the homogeneous islands are much wider than the lattice spacing, periodic stripes are better than checkerboard, bubbles, etc.

Summary

- Ising models with competing interactions are a natural “standard” model for stripe formation.
- Variational computations suggest that in the universal regime, where the homogeneous islands are much wider than the lattice spacing, periodic stripes are better than checkerboard, bubbles, etc.

Summary

- We proved striped periodicity of the minimizers, in $d = 1$, for all p , and in $d \geq 2$, for $p > 2d$.
- The proof combines localization bounds, based on a convenient droplet representation of the energy, with block reflection positivity.

Subtle aspect: control of the boundary errors in the localization procedure.

Summary

- We proved striped periodicity of the minimizers, in $d = 1$, for all p , and in $d \geq 2$, for $p > 2d$.
- The proof combines localization bounds, based on a convenient droplet representation of the energy, with block reflection positivity.

Subtle aspect: control of the boundary errors in the localization procedure.

Open problems

- 1 Generalize to $d < p \leq 2d$. In particular, do stripes form in $d = 2$ for $p = 3$ at large J ?
- 2 Prove stability of stripes (LRO) at positive temperatures in $d = 3$.
- 3 Are stripes stable in $d = 2$ at positive temperatures, or should we expect quasi-LRO (a'la Kosterlitz-Thouless)?

...

Open problems

- 1 Generalize to $d < p \leq 2d$. In particular, do stripes form in $d = 2$ for $p = 3$ at large J ?
- 2 Prove stability of stripes (LRO) at positive temperatures in $d = 3$.
- 3 Are stripes stable in $d = 2$ at positive temperatures, or should we expect quasi-LRO (a'la Kosterlitz-Thouless)?

...

Open problems

- 1 Generalize to $d < p \leq 2d$. In particular, do stripes form in $d = 2$ for $p = 3$ at large J ?
- 2 Prove stability of stripes (LRO) at positive temperatures in $d = 3$.
- 3 Are stripes stable in $d = 2$ at positive temperatures, or should we expect quasi-LRO (a'la Kosterlitz-Thouless)?

...

Open problems

- 1 Generalize to $d < p \leq 2d$. In particular, do stripes form in $d = 2$ for $p = 3$ at large J ?
- 2 Prove stability of stripes (LRO) at positive temperatures in $d = 3$.
- 3 Are stripes stable in $d = 2$ at positive temperatures, or should we expect quasi-LRO (a'la Kosterlitz-Thouless)?

...

Thank you!

Reflection positivity

Once we reduced to a local striped configuration, the model is effectively **one dimensional**:

$$H_{1D}(\underline{\sigma}) = -J \sum_x \sigma_x \sigma_{x+1} + \sum_{x < y} \sigma_x v(x-y) \sigma_y$$

where $v(x-y) \simeq 1/(y-x)^{p-1}$.

Reflection positivity

Once we reduced to a local striped configuration, the model is effectively **one dimensional**:

$$H_{1D}(\underline{\sigma}) = -J \sum_x \sigma_x \sigma_{x+1} + \sum_{x < y} \sigma_x v(x-y) \sigma_y$$

where $v(x-y) \simeq 1/(y-x)^{p-1}$.

Reflection positivity

Let us temporarily focus on the long range part:

$$H_0(\underline{\sigma}) = \sum_{x < y} \frac{\sigma_x \sigma_y}{(y - x)^{p-1}}$$

The goal is to find the minimizing configuration $\underline{\sigma}$.

The key idea to implement is **reflection positivity**:

Reflection positivity

Let us temporarily focus on the long range part:

$$H_0(\underline{\sigma}) = \sum_{x < y} \frac{\sigma_x \sigma_y}{(y - x)^{p-1}}$$

The goal is to find the minimizing configuration $\underline{\sigma}$.

The key idea to implement is **reflection positivity**:

$$\frac{1}{(y - x)^{p-1}} = c_p \int_0^\infty d\alpha \alpha^{p-2} e^{-\alpha(y-x)}$$

Reflection positivity

Let us temporarily focus on the long range part:

$$H_0(\underline{\sigma}) = \sum_{x < y} \frac{\sigma_x \sigma_y}{(y - x)^{p-1}}$$

The goal is to find the minimizing configuration $\underline{\sigma}$.

The key idea to implement is **reflection positivity**:

$$H_0(\underline{\sigma}_L, \underline{\sigma}_R) = E_L(\underline{\sigma}_L) + E_R(\underline{\sigma}_R) + \\ + c_p \int_0^\infty d\alpha \alpha^{p-2} \sum_{x \leq 0} \sum_{y \geq 1} \sigma_x \sigma_y e^{-\alpha y} e^{\alpha x}$$

Reflection positivity

Let us temporarily focus on the long range part:

$$H_0(\underline{\sigma}) = \sum_{x < y} \frac{\sigma_x \sigma_y}{(y - x)^{p-1}}$$

The goal is to find the minimizing configuration $\underline{\sigma}$.

The key idea to implement is **reflection positivity**:

$$H_0(\underline{\sigma}_L, \underline{\sigma}_R) = E_L(\underline{\sigma}_L) + E_R(\underline{\sigma}_R) - \\ -c_p \int_0^\infty d\alpha \alpha^{p-2} \sum_{x, y \geq 1} (\theta \underline{\sigma}_L)_x \sigma_y e^{-\alpha y} e^{-\alpha x} e^\alpha$$

Reflection positivity

Let us temporarily focus on the long range part:

$$H_0(\underline{\sigma}) = \sum_{x < y} \frac{\sigma_x \sigma_y}{(y - x)^{p-1}}$$

The goal is to find the minimizing configuration $\underline{\sigma}$.

The key idea to implement is **reflection positivity**:

$$H_0(\underline{\sigma}_L, \underline{\sigma}_R) = E_L(\underline{\sigma}_L) + E_R(\underline{\sigma}_R) - \\ -c_p \int_0^\infty d\alpha \alpha^{p-2} e^{-\alpha} \left[\sum_{x \geq 1} (\theta \underline{\sigma}_L)_x e^{-\alpha(x-1)} \right] \left[\sum_{y \geq 1} \sigma_y e^{-\alpha(y-1)} \right]$$

Reflection positivity

Let us temporarily focus on the long range part:

$$H_0(\underline{\sigma}) = \sum_{x < y} \frac{\sigma_x \sigma_y}{(y - x)^{p-1}}$$

The goal is to find the minimizing configuration $\underline{\sigma}$.

The key idea to implement is **reflection positivity**:

$$H_0(\underline{\sigma}_L, \underline{\sigma}_R) = E_L(\underline{\sigma}_L) + E_R(\underline{\sigma}_R) - \langle \theta \underline{\sigma}_L, \underline{\sigma}_R \rangle$$

Reflection positivity

Let us temporarily focus on the long range part:

$$H_0(\underline{\sigma}) = \sum_{x < y} \frac{\sigma_x \sigma_y}{(y - x)^{p-1}}$$

The goal is to find the minimizing configuration $\underline{\sigma}$.

The key idea to implement is **reflection positivity**:

$$\begin{aligned} H_0(\underline{\sigma}_L, \underline{\sigma}_R) &= E_L(\underline{\sigma}_L) + E_R(\underline{\sigma}_R) - \langle \theta \underline{\sigma}_L, \underline{\sigma}_R \rangle \\ &\geq E_L(\underline{\sigma}_L) + E_R(\underline{\sigma}_R) - \frac{1}{2} \langle \theta \underline{\sigma}_L, \theta \underline{\sigma}_L \rangle - \frac{1}{2} \langle \underline{\sigma}_R, \underline{\sigma}_R \rangle \end{aligned}$$

Reflection positivity

Let us temporarily focus on the long range part:

$$H_0(\underline{\sigma}) = \sum_{x < y} \frac{\sigma_x \sigma_y}{(y - x)^{p-1}}$$

The goal is to find the minimizing configuration $\underline{\sigma}$.

The key idea to implement is **reflection positivity**:

$$\begin{aligned} H_0(\underline{\sigma}_L, \underline{\sigma}_R) &= E_L(\underline{\sigma}_L) + E_R(\underline{\sigma}_R) - \langle \theta \underline{\sigma}_L, \underline{\sigma}_R \rangle \\ &\geq \frac{1}{2} E(\underline{\sigma}_L, \theta \underline{\sigma}_L) + \frac{1}{2} E(\theta \underline{\sigma}_R, \underline{\sigma}_R) \end{aligned}$$

Block reflection positivity

Summarizing: the long range energy decreases by reflecting left onto right, or viceversa. If $J > 0$, then we can reflect only at the “broken bonds”:

$$\begin{array}{c} \boxed{h_1} \quad \boxed{h_2} \quad \boxed{h_3} \quad \boxed{h_4} \\ \geq \\ \geq \frac{1}{2} \boxed{h_4} \quad \boxed{h_3} \quad \boxed{h_3} \quad \boxed{h_4} + \frac{1}{2} \boxed{h_1} \quad \boxed{h_2} \quad \boxed{h_2} \quad \boxed{h_1} \end{array}$$

After repeated reflections we end up with a lower bound involving periodic arrays of blocks all of the same size $\dots, h_i, h_i, h_i, h_i, \dots$

Block reflection positivity

Summarizing: the long range energy decreases by reflecting left onto right, or viceversa. If $J > 0$, then we can reflect only at the “broken bonds”:

$$\begin{array}{c} \boxed{h_1} \quad \boxed{h_2} \quad \boxed{h_3} \quad \boxed{h_4} \\ \geq \\ \geq \frac{1}{2} \boxed{h_4} \quad \boxed{h_3} \quad \boxed{h_3} \quad \boxed{h_4} + \frac{1}{2} \boxed{h_1} \quad \boxed{h_2} \quad \boxed{h_2} \quad \boxed{h_1} \end{array}$$

After repeated reflections we end up with a lower bound involving periodic arrays of blocks all of the same size $\dots, h_i, h_i, h_i, h_i, \dots$