

# On the non-equilibrium fluctuations of partial exclusion with open boundary

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Inhomogeneous Random Systems

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## *The plan for today's lecture:*

- ① Exclusion (ONE particle per site): hydrodynamics and fluctuations
- ② Partial exclusion ( $\alpha$  particles per site)
- ③ Correlation estimates

*Joint with*

**Chiara Franceschini, Milton Jara, Beatriz Salvador**



## The dynamics:

- For  $N \geq 1$  let  $\Lambda_N = \{1, \dots, N-1\}$ .
- We denote the process by  $\{\eta_t : t \geq 0\}$  which has state space  $\Omega_N := \{0, 1\}^{\Lambda_N}$ .
- The infinitesimal generator  $\mathcal{L}_N = \mathcal{L}_{N,0} + \mathcal{L}_{N,b}$  is given on  $f : \Omega_N \rightarrow \mathbb{R}$ , by

$$(\mathcal{L}_{N,0}f)(\eta) = \sum_{x=1}^{N-2} c_{x,x+1}(\eta) \left( f(\eta^{x,x+1}) - f(\eta) \right),$$

$$(\mathcal{L}_{N,b}f)(\eta) = \frac{\kappa}{N^\theta} \sum_{x \in \{1, N-1\}} c_{r_x}(\eta(x)) \left( f(\eta^x) - f(\eta) \right),$$

where  $c_{x,x+1}(\eta) := \eta(x)(1 - \eta(x+1)) + \eta(x+1)(1 - \eta(x))$ ,  
for  $x = 1$  and  $x = N-1$ ,

$$c_{r_x}(\eta(x)) = r_x(1 - \eta(x)) + (1 - r_x)\eta(x),$$

$$r_1 = \alpha \text{ and } r_{N-1} = \beta.$$

## Invariant measures:

- ♣ If  $\alpha = \beta = \rho$  the Bernoulli product measures are invariant (equilibrium measures):  $\nu_\rho(\eta : \eta(x) = 1) = \rho$ .
- ♣ If  $\alpha \neq \beta$  the Bernoulli product measure is no longer invariant, but since we have a finite state irreducible Markov process there exists a UNIQUE invariant measure: the stationary measure (non-equilibrium) denoted by  $\mu_{ss}$ .
- ♣ By the matrix ansatz method one can get information about this measure. (Not for the partial exclusion!)

# Hydrodynamics

## Hydrodynamic Limit:

♣ For  $\eta \in \Omega_N$ , let  $\pi_t^N(\eta, dq) = \frac{1}{N} \sum_{x=1}^{N-1} \eta_{tN^2}(x) \delta_{x/N}(dq)$ , be the *empirical measure*. (*Diffusive time scaling!*)

♣ Assumption: fix  $g : [0, 1] \rightarrow [0, 1]$  measurable and probability measures  $\{\mu_N\}_{N \geq 1}$  such that for every  $H \in C([0, 1])$ ,

$$\frac{1}{N} \sum_{x=1}^{N-1} H\left(\frac{x}{N}\right) \eta(x) \xrightarrow{N \rightarrow +\infty} \int_0^1 H(q) g(q) dq,$$

wrt  $\mu_N$ . ( $\mu_N$  is associated to  $g(\cdot)$ )

♣ Then: for any  $t > 0$ ,

$$\pi_t^N(\eta, dq) \xrightarrow{N \rightarrow +\infty} \rho(t, q) dq,$$

wrt  $\mu_N(t)$ , where  $\rho(t, q)$  evolves according to a PDE, the *hydrodynamic equation*.

## Hydrodynamic Limit:

### **Theorem [Baldasso et al]:**

Let  $g : [0, 1] \rightarrow [0, 1]$  be a measurable function and let  $\{\mu_N\}_{N \geq 1}$  be a sequence of probability measures in  $\Omega_N$  associated to  $g(\cdot)$ . Then, for any  $0 \leq t \leq T$ ,

$$\lim_{N \rightarrow \infty} \mathbb{P}_{\mu_N} \left( \left| \frac{1}{N} \sum_{x \in \Lambda_N} H\left(\frac{x}{N}\right) \eta_{tN^2}(x) - \int_0^1 H(q) \rho(t, q) dq \right| > \delta \right) = 0$$

and  $\rho_t(\cdot)$  is the UNIQUE weak solution of the heat equation  $\partial_t \rho_t(q) = \partial_q^2 \rho_t(q)$  with

♣  $\theta > 1$  **Neumann b.c.:**  $\partial_q \rho_t(0) = \partial_q \rho_t(1) = 0$ .

♣  $\theta = 1$  **Robin b.c.:**

$$\partial_q \rho_t(0) = \kappa(\rho_t(0) - \alpha), \quad \partial_q \rho_t(1) = \kappa(\beta - \rho_t(1)).$$

♣  $\theta < 1$  **Dirichlet b.c.:**  $\rho_t(0) = \alpha, \rho_t(1) = \beta$ .

# Fluctuations



## Non-equilibrium fluctuations ( $\theta \geq 0$ ):

### Definition (Density fluctuation field)

The density fluctuation field  $\mathcal{Y}^N$  is the time-trajectory of linear functionals acting on functions  $H \in \mathcal{S}_\theta$  as

$$\mathcal{Y}_t^N(H) = \frac{1}{\sqrt{N}} \sum_{x=1}^{N-1} H\left(\frac{x}{N}\right) \left( \eta_{tN^2}(x) - \mathbb{E}_{\mu_N}[\eta_{tN^2}(x)] \right).$$

### Definition (The space of test functions)

Let  $\mathcal{S}_\theta$  denote the set of functions  $H \in C^\infty([0,1])$  such that for any  $k \in \mathbb{N} \cup \{0\}$  it holds that

- 1 for  $\theta < 1$ :  $\partial_u^{2k} H(0) = \partial_u^{2k} H(1) = 0$ ;
- 2 for  $\theta = 1$ :  
 $\partial_u^{2k+1} H(0) = \partial_u^{2k} H(0), \quad \partial_u^{2k+1} H(1) = -\partial_u^{2k} H(1)$ ;
- 3 for  $\theta > 1$ :  $\partial_u^{2k+1} H(0) = \partial_u^{2k+1} H(1) = 0$ .

Fluctuations:  $\theta = 1$

## What are the conditions on the initial state $\mu_N$ ?:

- For each  $N \in \mathbb{N}$ , the measure  $\mu_N$  is associated to a measurable profile  $\rho_0 : [0, 1] \rightarrow [0, 1]$   
(This is the same condition for hydrodynamics!).
- For  $\rho_0^N(x) = \mathbb{E}_{\mu_N}[\eta_0(x)]$

$$\max_{x \in \Lambda_N} \left| \rho_0^N(x) - \rho_0\left(\frac{x}{N}\right) \right| \lesssim \frac{1}{N}.$$

- For

$$\varphi_0^N(x, y) = \mathbb{E}_{\mu_N}[\eta(x)\eta(y)] - \rho_0^N(x)\rho_0^N(y)$$

it holds that

$$\max_{1 \leq x < y \leq N-1} |\varphi_0^N(x, y)| \lesssim \frac{1}{N}.$$

## Examples of initial measures $\mu_N$ :

- If for a given measurable profile  $\rho_0 : [0, 1] \rightarrow [0, 1]$ , we take  $\mu_N$  as the Bernoulli product measure with marginal given by

$$\mu_N\{\eta : \eta(x) = 1\} = \rho_0\left(\frac{x}{N}\right)$$

then all the conditions above are true.

- If  $\mu_{ss}$  is the stationary measure, then all the conditions above are true, by choosing the profile  $\rho_0$  as the stationary profile  $\bar{\rho}$  given by

$$\bar{\rho}(q) = \begin{cases} (\beta - \alpha)q + \alpha; & \theta < 1, \\ \frac{\kappa(\beta - \alpha)}{2 + \kappa}q + \alpha + \frac{\beta - \alpha}{2 + \kappa}; & \theta = 1, \\ \frac{\beta + \alpha}{2}; & \theta > 1. \end{cases}$$



## Theorem [Ornstein-Uhlenbeck limit]:

If  $\{\mathcal{Y}_0^N\}_{N \in \mathbb{N}}$  converges, as  $N \rightarrow \infty$ , to a mean-zero Gaussian field with covariance  $\mathbb{E}[\mathcal{Y}_0(H)\mathcal{Y}_0(G)] := \sigma(H, G)$ , then, the sequence  $\{\mathcal{Q}_N\}_{N \in \mathbb{N}}$  converges, as  $N \rightarrow \infty$ , to a generalized Ornstein-Uhlenbeck process:

$$\partial_t \mathcal{Y}_t = \Delta_1 \mathcal{Y}_t dt + \sqrt{2\chi(\rho_t)} \nabla_1 \mathcal{W}_t,$$

where  $\mathcal{W}_t$  is a space-time white noise of unit variance. As a consequence, for  $H, G \in \mathcal{S}_\theta$  it holds

$$\begin{aligned} \mathbb{E}[\mathcal{Y}_t(H)\mathcal{Y}_s(G)] &= \sigma(T_t^1 H, T_s^1 G) \\ &+ \int_0^s \langle \nabla_1 T_{t-r}^1 H, \nabla_1 T_{s-r}^1 G \rangle_{L^{2,1}(\rho_r)} dr. \end{aligned}$$

Above  $T_t^\theta : \mathcal{S}_\theta \rightarrow \mathcal{S}_\theta$  is the semigroup associated to the PDE with the corresponding boundary conditions with  $\alpha = \beta = 0$ .

## Associated martingales:

Let  $H : [0, 1] \rightarrow \mathbb{R}$  be a test function and note that

$$\mathcal{M}_t^N(H) := \mathcal{Y}_t^N(H) - \mathcal{Y}_0^N(H) - \int_0^t N^2 \mathcal{L}_N \mathcal{Y}_s^N(H) ds$$

is a martingale where

$$\begin{aligned} N^2 \mathcal{L}_N \mathcal{Y}_s^N(H) &= \frac{1}{\sqrt{N}} \sum_{x=1}^{N-1} \Delta_N H\left(\frac{x}{N}\right) \left( \eta_{sN^2}(x) - \rho_s^N(x) \right) \\ &\quad + \sqrt{N} \left[ \nabla_N^+ H(0) - H\left(\frac{1}{N}\right) \right] \bar{\eta}_{sN^2}(1) \\ &\quad + \sqrt{N} \left[ H\left(\frac{N-1}{N}\right) + \nabla_N^- H(1) \right] \bar{\eta}_{sN^2}(N-1). \end{aligned}$$

Recall that for  $\theta = 1$ :  $H'(0) = H(0)$  and  $H'(1) = -H(1)$ . Note that the first term at the right-hand side of the previous expression is  $\mathcal{Y}_s^N(\Delta_N H)$ . Above,

$$\nabla_N^+ H(x) = N \left[ H\left(\frac{x+1}{N}\right) - H\left(\frac{x}{N}\right) \right], \quad \nabla_N^- H(x) = N \left[ H\left(\frac{x}{N}\right) - H\left(\frac{x-1}{N}\right) \right].$$

## The correlation estimate:

### Definition (Two-point correlation function)

For  $x, y \in V_N = \{(x, y); x, y \in \mathbb{N}, 0 < x < y < N\}$ ,  $t \in [0, T]$ ,

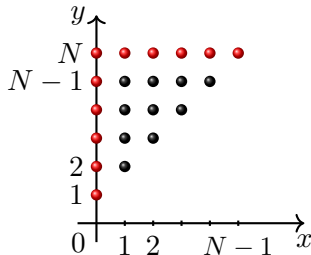
$$\varphi_t^N(x, y) = \mathbb{E}_{\mu_N}[\eta_{tN^2}(x)\eta_{tN^2}(y)] - \rho_t^N(x)\rho_t^N(y),$$

and set  $\varphi_t^N(x, y) = 0$ , for  $x = 0$  or  $y = N$ .

### Proposition:

If  $\max_{x, y \in V_N} |\varphi_0^N(x, y)| \lesssim \frac{1}{N}$ , then

$$\sup_{t \geq 0} \max_{(x, y) \in V_N} |\varphi_t^N(x, y)| \lesssim \frac{1}{N}.$$



Fluctuations :  $\theta \neq 1$



## *Non-equilibrium fluctuations ( $\theta \neq 1$ ):*

$$\begin{aligned} N^2 \mathcal{L}_N \mathcal{Y}_s^N(H) &= \frac{1}{\sqrt{N}} \sum_{x=1}^{N-1} \Delta_N H\left(\frac{x}{N}\right) \left( \eta_{sN^2}(x) - \rho_s^N(x) \right) \\ &\quad + \sqrt{N} \nabla_N^+ H(0) \bar{\eta}_{sN^2}(1) - \sqrt{N} \nabla_N^- H(1) \bar{\eta}_{sN^2}(N-1) \\ &\quad - \frac{N^{3/2}}{N^\theta} H\left(\frac{1}{N}\right) \bar{\eta}_{sN^2}(1) - \frac{N^{3/2}}{N^\theta} H\left(\frac{N-1}{N}\right) \bar{\eta}_{sN^2}(N-1). \end{aligned}$$



### Lemma:

For  $x \in \{1, N-1\}$  and  $t \in [0, T]$  it holds that

$$\mathbb{E}_{\mu_N} \left[ \left( \int_0^t C_N^\theta (\eta_{sN^2}(x) - \rho_s^N(x)) ds \right)^2 \right] \lesssim (C_N^\theta)^2 \frac{N^\theta}{N^2}.$$

We apply last result with  $C_N^\theta = \sqrt{N} \mathbf{1}_{\{\theta < 1\}} + N^{3/2-\theta} \mathbf{1}_{\{\theta > 1\}}$ .

## *The initial measures:*

Fix  $\rho_0 : [0, 1] \rightarrow [0, 1]$  measurable and of class  $C^6$ , and assume

$$\max_{x \in \Lambda_N} |\rho_0^N(x) - \rho_0(\frac{x}{N})| \lesssim \frac{1}{N}, \quad \max_{(x,y) \in V_N} |\varphi_0^N(x,y)| \lesssim \frac{1}{N}, \quad (1)$$

$$\max_{y \in \Lambda_N} |\varphi_0^N(x,y)| \lesssim \begin{cases} \frac{N^\theta}{N^2}, & \theta \leq 1, \\ \frac{1}{N}, & \theta \geq 1, \end{cases} \quad \text{for } x = 1, N-1. \quad (2)$$



### **Proposition:**

If (1) and (2) hold, then

$$\sup_{t \geq 0} \max_{(x,y) \in V_N} |\varphi_t^N(x,y)| \lesssim \frac{1}{N},$$

$$\sup_{t \geq 0} \max_{y \in \Lambda_N} |\varphi_t^N(x,y)| \lesssim \begin{cases} \frac{N^\theta}{N^2}, & \theta \leq 1, \\ \frac{1}{N}, & \theta \geq 1, \end{cases} \quad \text{for } x = 1, N-1.$$

## *Ingredients for the correlation estimate:*

Show that  $\rho_t^N(\cdot)$  is a solution of

$$\begin{cases} \partial_t \rho_t^N(x) = (N^2 \mathfrak{B}_N^\theta \rho_t^N)(x), & x \in \Lambda_N, \quad t \geq 0, \\ \rho_t^N(0) = \alpha, \rho_t^N(N) = \beta, & t \geq 0, \end{cases}$$

where  $\mathfrak{B}_N^\theta$  acts on  $f : \Lambda_N \cup \{0, N\} \rightarrow \mathbb{R}$  as

$$(\mathfrak{B}_N^\theta f)(x) = \sum_{y=0}^N \xi_{x,y}^{N,\theta} (f(y) - f(x)), \quad \text{for } x \in \Lambda_N$$

and it is the infinitesimal generator of the RW in  $\bar{\Lambda}_N$  which is absorbed at the points  $\{0, N\}$ . Above

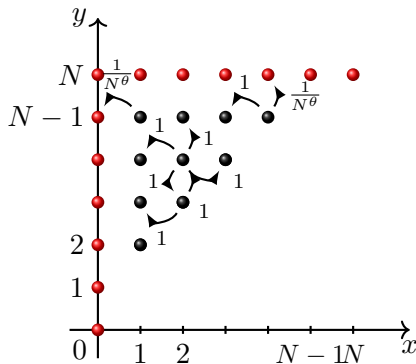
$$\xi_{x,y}^{N,\theta} = \begin{cases} 1, & \text{if } |y - x| = 1 \text{ and } x, y \in \Lambda_N, \\ N^{-\theta}, & \text{if } x = 1, y = 0 \text{ and } x = N - 1, y = N, \\ 0, & \text{otherwise.} \end{cases}$$

## *Ingredients for the correlation estimate:*

Then  $\varphi_t^N(x, y)$  is solution of

$$\begin{cases} \partial_t \varphi_t^N(x, y) = N^2 \mathcal{A}_N^\theta \varphi_t^N(x, y) - (\nabla_N^+ \rho_t^N(x))^2 \delta_{y=x+1}, (x, y) \in V_N, \\ \varphi_t^N(x, y) = 0, (x, y) \in \partial V_N. \end{cases}$$

Above  $\mathcal{A}_N^\theta$  is the infinitesimal generator of a random walk  $\mathcal{X}_{tN^2}$  in  $V_N \cup \partial V_N$  which is absorbed at  $\partial V_N$  with rate  $N^{-\theta}$ .



## How to get bounds?

By Duhamel's formula

$$\varphi_t^N(x, y) = \mathbb{E}_{(x, y)} \left[ \varphi_0^N(\mathcal{X}_{tN^2}) + \int_0^t g_{t-s}^N(\mathcal{X}_{sN^2}) \mathbf{1}(\mathcal{X}_{sN^2} \in \mathcal{D}_N^+) ds \right],$$

where  $\mathbb{E}_{(x, y)}$  denotes the expectation of the law of the walk  $\{\mathcal{X}_{tN^2}; t \geq 0\}$  starting from  $(x, y)$ ,

$$g_t^N(x, x+1) = - \left( \nabla_N^+ \rho_t^N(x) \right)^2, \text{ and}$$

$\mathcal{D}_N^+ := \{(x, y) \in V_N : y = x + 1\}$ . Therefore, it is enough to estimate

$$\max_{\substack{(z, w) \in V_N \\ z \neq w}} |\varphi_0^N(z, w)| + \sup_{t \geq 0} \max_{z \in \Lambda_{N-1}} |g_t^N(z, z+1)| \max_{\substack{(x, y) \in V_N \\ x \neq y}} T_N(x, y),$$

where

$$T_N(x, y) := \mathbb{E}_{(x, y)} \left[ \int_0^\infty \mathbf{1}(\mathcal{X}_{tN^2} \in \mathcal{D}_N^+) dt \right]$$

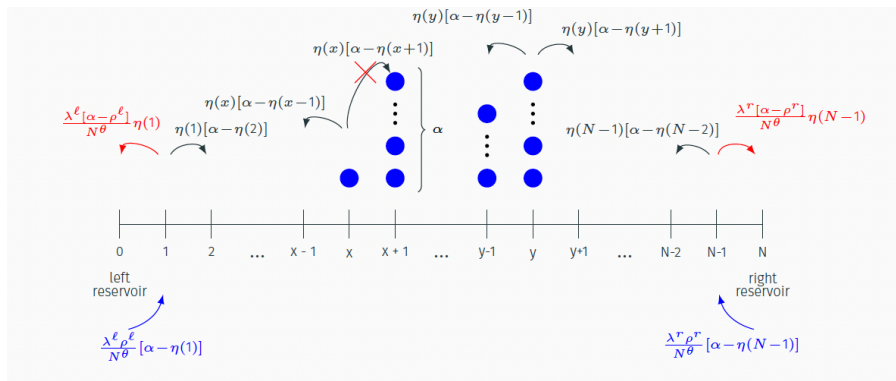
is the time spent by the walk on the diagonal  $\mathcal{D}_N^+$ .

## *Estimating the correlation function?*

For estimating  $g_t^N$  we need to estimate the time spent by a  $1 - d$  RW at the points  $x = 1$  and  $x = N - 1$  and if it is the absorbed one, then this is of order  $O(\frac{N^\theta}{N^2})$  (good bound when  $\theta < 1$  but not when  $\theta > 1$ ). When  $\theta > 1$  we compare with the reflected RW and we prove that the time now is of order  $O(\frac{1}{N})$ .

For estimating  $\varphi_t^N$  we also need the same type of estimates in the  $2 - d$  setting for the time spent by the RW on the diagonal  $\mathcal{D}_N^+$ . For  $\theta < 1$  we use the absorbed RW but for  $\theta > 1$  we use the reflected RW.

# Partial Exclusion:



$\alpha \in \mathbb{N}$ ,  $\lambda_\ell, \lambda_r \in (0, 1]$  and  $\rho_\ell, \rho_r \in (0, \alpha)$ ,  $\theta \in \mathbb{R}$ .

## Hydrodynamic Limit:



### Theorem [Franceschini, G., Salvador]:

Let  $g : [0, 1] \rightarrow [0, 1]$  be a measurable function and let  $\{\mu_N\}_{N \geq 1}$  be a sequence of probability measures in  $\Omega_N$  associated to  $g(\cdot)$ . Then, for any  $0 \leq t \leq T$ ,

$$\lim_{N \rightarrow \infty} \mathbb{P}_{\mu_N} \left( \left| \frac{1}{N} \sum_{x \in \Lambda_N} H\left(\frac{x}{N}\right) \eta_{tN^2}(x) - \int_0^1 H(q) \rho(t, q) dq \right| > \delta \right) = 0$$

and  $\rho_t(\cdot)$  is the UNIQUE weak solution of the heat equation  $\partial_t \rho_t(q) = \alpha \partial_q^2 \rho_t(q)$  with

♣  $\theta > 1$  **Neumann b.c.:**  $\partial_q \rho_t(0) = \partial_q \rho_t(1) = 0$ .

♣  $\theta = 1$  **Robin b.c.:**

$$\partial_q \rho_t(0) = \lambda^\ell (\rho_t(0) - \rho^\ell) \quad \partial_q \rho_t(1) = \lambda^r (\rho^r - \rho_t(1)).$$

♣  $\theta < 1$  **Dirichlet b.c.:**  $\rho_t(0) = \rho^\ell, \rho_t(1) = \rho^r$ .



## Different definition?

It would be natural to extend  $\varphi_t^N$  to the diagonal by

$$\varphi_t^N(x, x) := \mathbb{E}_{\mu^N} [(\eta_{tN^2}(x) - \rho_t^N(x))^2].$$

A more convenient definition is to extend it as

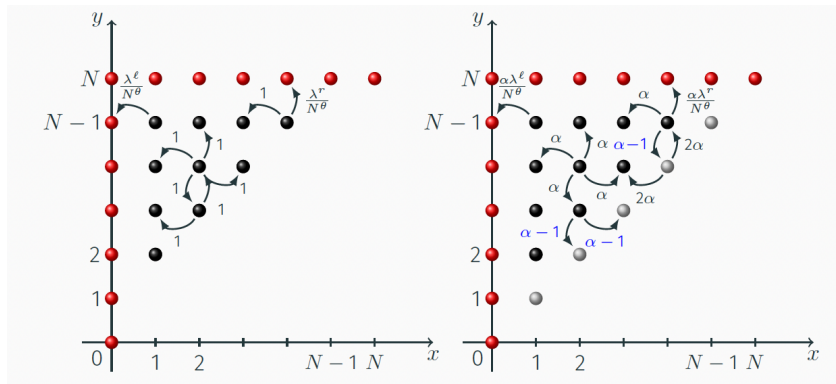
$$\varphi_t^N(x, x) := \mathbb{E}_{\mu^N} \left[ \frac{\alpha}{\alpha - 1} \eta_{tN^2}(x) (\eta_{tN^2}(x) - 1) - \rho_t^N(x)^2 \right].$$

In this case we also have

$$\left\{ \begin{array}{l} \partial_t \varphi_t^N(x, y) = N^2 \mathcal{A}_N^\theta \varphi_t^N(x, y) - (\nabla_N^+ \rho_t^N(x))^2 \delta_{y=x+1}, (x, y) \in V_N, \\ \varphi_t^N(x, y) = 0, (x, y) \in \partial V_N, \\ \varphi_0^N(x, y) = \mathbb{E}_{\mu_N} [\eta_0(x) \eta_0(y)] - \rho_0^N(x) \rho_0^N(y), (x, y) \in V_N \cup \partial V_N, \end{array} \right.$$

but the operator  $\mathcal{A}_N^\theta$  is different from the one in SEP(1).

# Another RW



(I JUMP TO THE BOARD NOW!).

## *What about $\theta$ negative?*

We expect the same behavior as  $\theta \in [0, 1)$  - DIRICHLET!

In this case the space of test functions that we take is  $\mathcal{S}_\theta$  composed of functions  $H \in C^\infty([0, 1])$  such that for any  $k \in \mathbb{N} \cup \{0\}$  it holds  $\partial_u^k H(0) = \partial_u^k H(1) = 0$ .

Now all the derivatives are null at the boundary!!! Our result says that if  $\theta < 0$ , the sequence  $\{\mathbb{Q}_N\}_{N \in \mathbb{N}}$  converges, as  $N \rightarrow +\infty$ , to the generalized Ornstein-Uhlenbeck process as in the case  $\theta \in [0, 1)$  since  $\mathcal{Y}_t$  satisfies the conditions:

- 1 regularity condition:  $\mathbb{E}[(\mathcal{Y}_t(H))^2] \lesssim \|H\|_{L^2}$ , for any  $H \in \mathcal{S}_\theta$ ;
- 2 boundary condition: for any  $t \in [0, T]$  and  $j \in \{0, 1\}$ , it holds that

$$\lim_{\epsilon \rightarrow 0} \mathbb{E}_{\mu_N} \left[ \left( \int_0^t \mathcal{Y}_s(\iota_\epsilon^j) ds \right)^2 \right] = 0,$$

where for  $u \in [0, 1]$  and:  $j = 0$ ,  $\iota_\epsilon^0(u) := \epsilon^{-1} \mathbf{1}_{(0, \epsilon]}(u)$  and, for  $j = 1$ ,  $\iota_\epsilon^1(u) := \epsilon^{-1} \mathbf{1}_{[1-\epsilon, 1)}(u)$ .

## And now?

- ① Estimates for  $k$ -points correlations?
  - ① How to define the correlation function?
  - ② How to control static equations?
  - ③ Is the bound equal to SEP(1)?
- ② What about other models with duality?

*T h a n k   y o u !*

*M e r c i !*

*O b r i g a d a !*